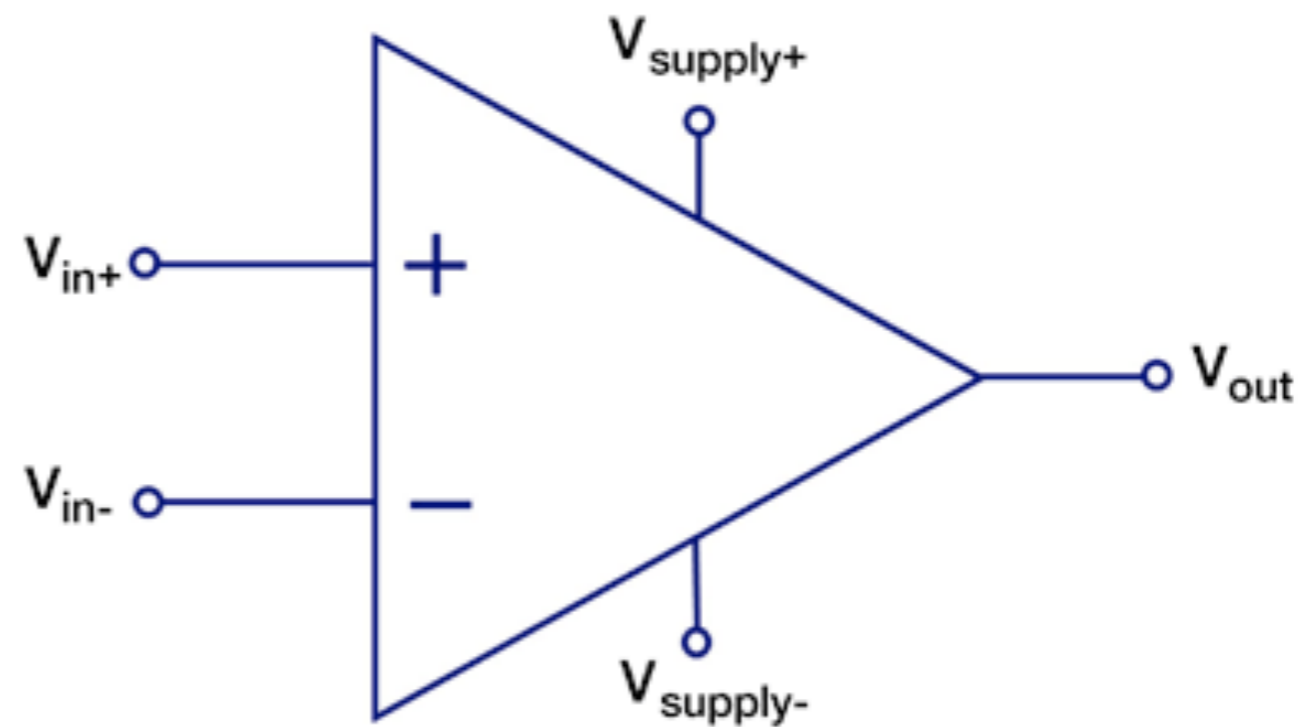
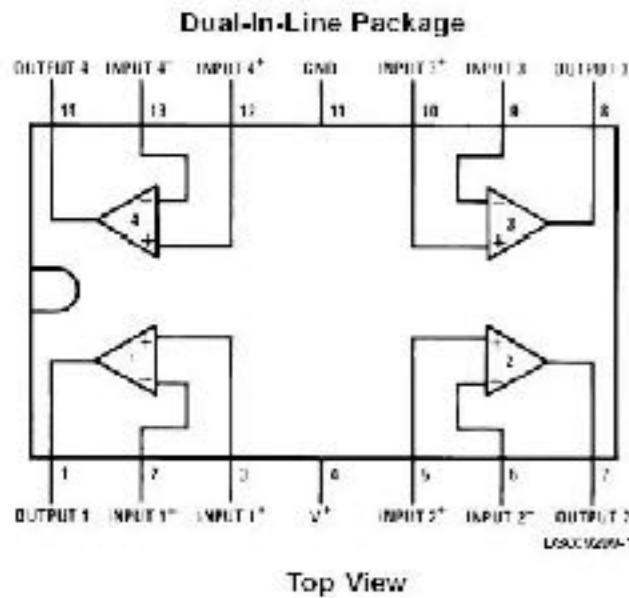
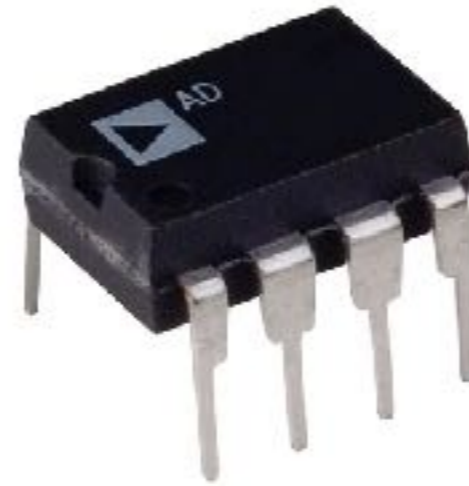


Sensors, Microcontrollers and Actuators

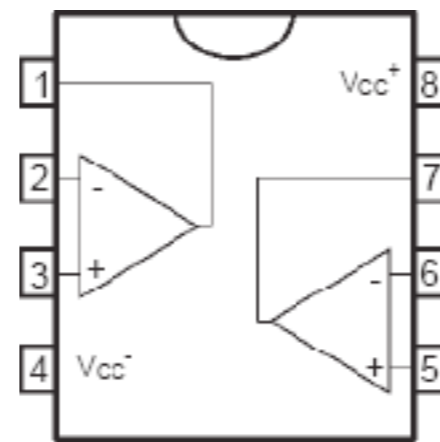
Operational Amplifiers



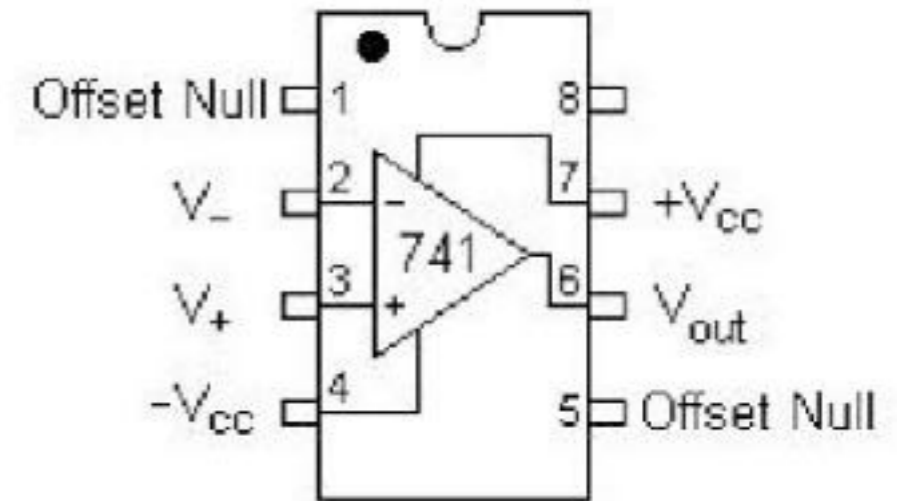
Package and pin-out



Quad opamp



Dual opamp

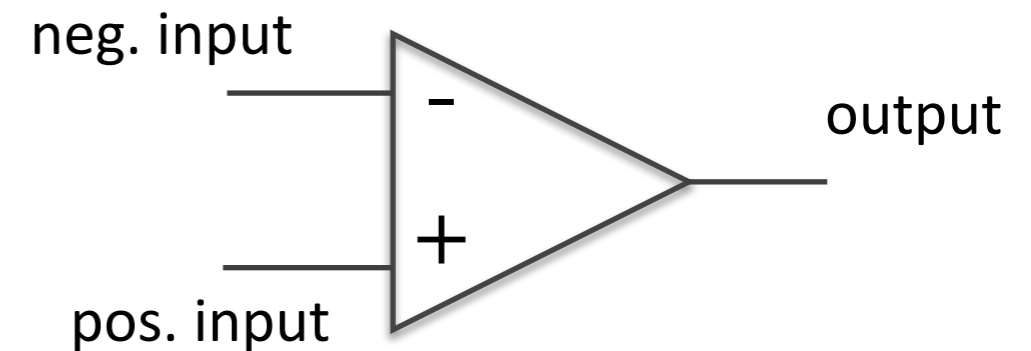


Single opamp

Operational amplifiers

An OPAMP is an **ideal** electronic building block:

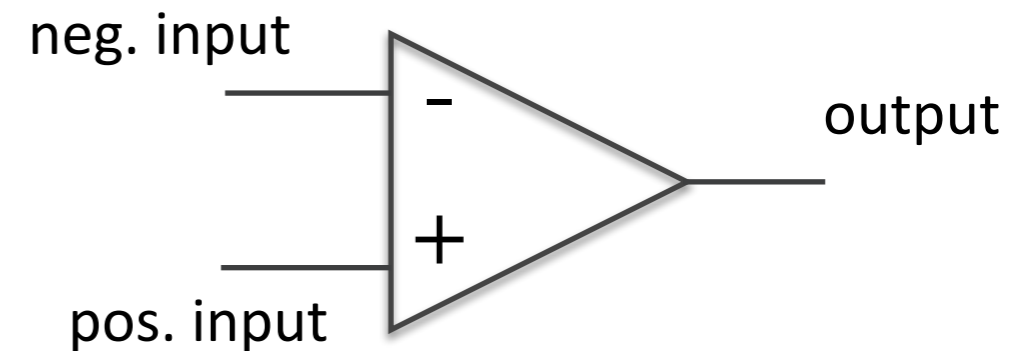
1. The opamp has a very high amplification (infinite)



Operational amplifiers

An OPAMP is an **ideal** electronic building block:

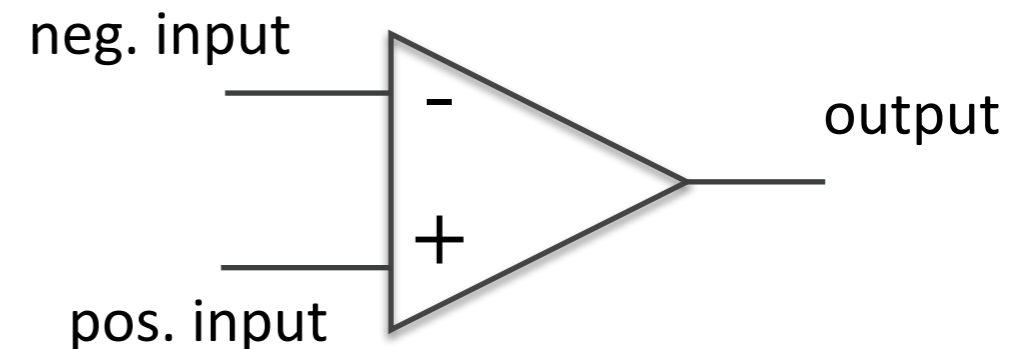
1. The opamp has a very high amplification (infinite)
2. The input impedance (resistance) is very high ... so *the input-current is incredibly low (= zero).*



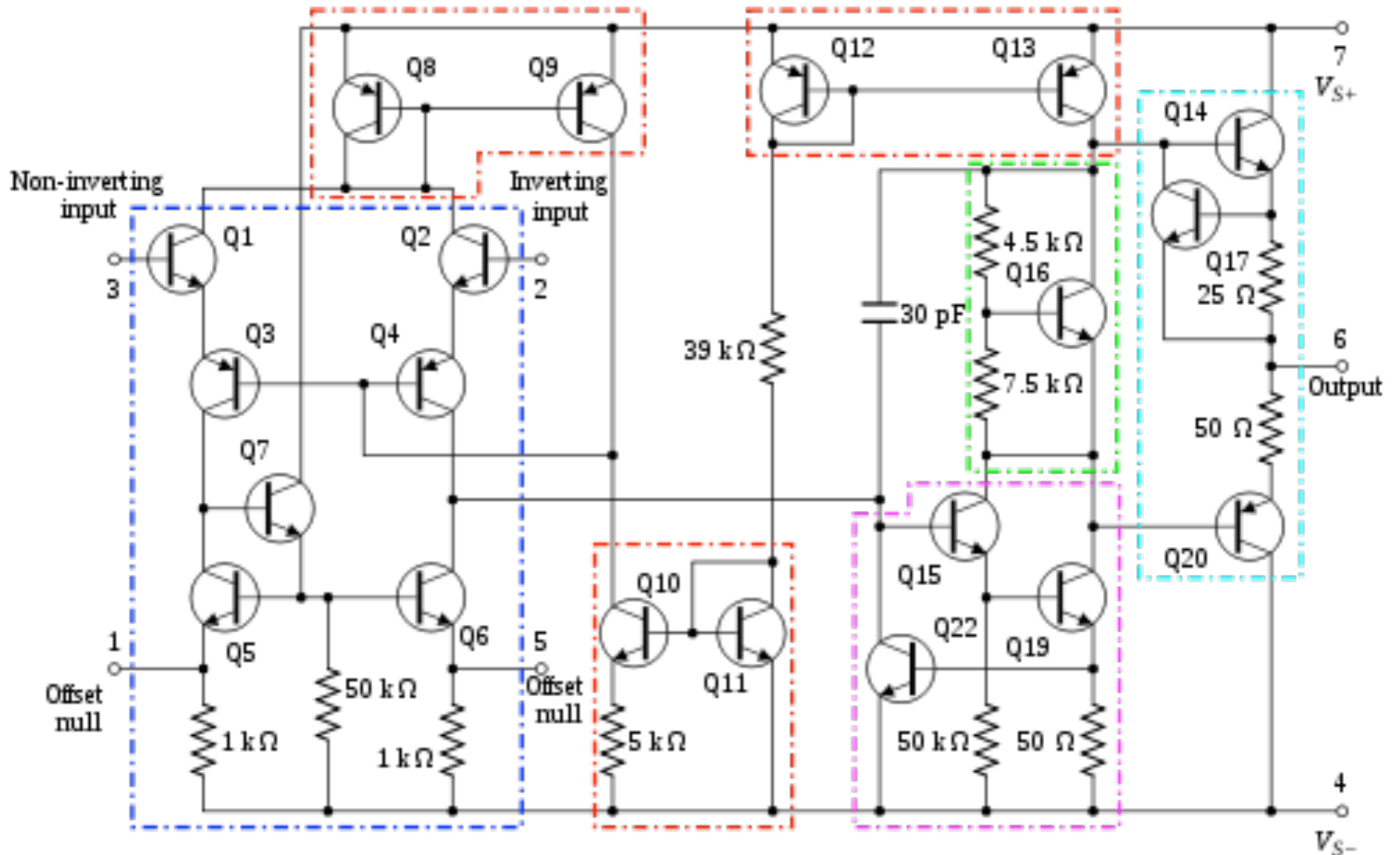
Operational amplifiers

An OPAMP is an **ideal** electronic building block:

1. The opamp has a very high amplification (infinite)
2. The input impedance (resistance) is very high ... so *the input-current is incredibly low (=zero).*
3. The output impedance is very low ... so *the opamp can deliver high currents*



Inside the Opamp ...

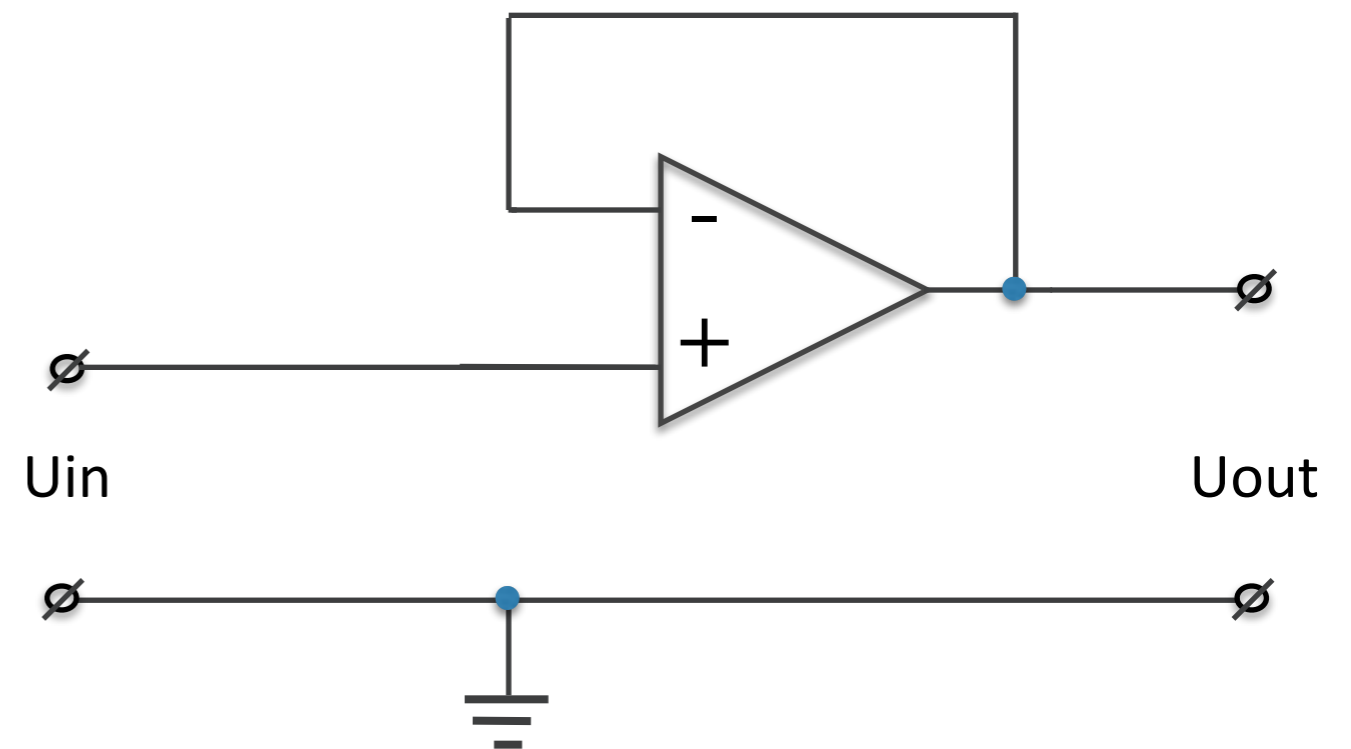


Some practical circuits, used in sensor world ...

Some practical circuits, used in sensor world ...

Signal Buffer

Suppose you have to connect your sensor to more circuits, or sharing it with others, or driving it over long cables (installation). In that case it's wise to make use of buffers. Buffer circuits (in this case follower) act as buffer between the sensor output (weak fragile signal) and the "outside world".



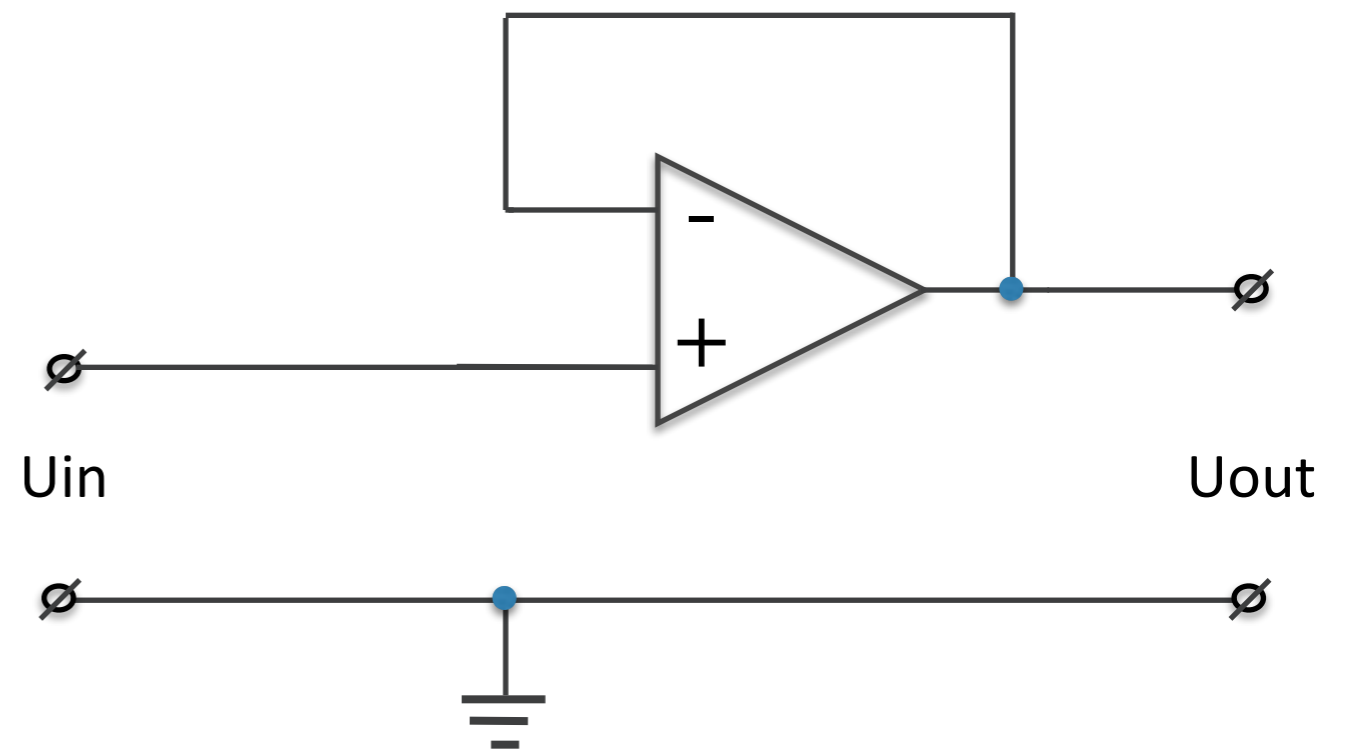
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$$A_u = \text{Amplification} = 1 \quad (= 0\text{dB})$$

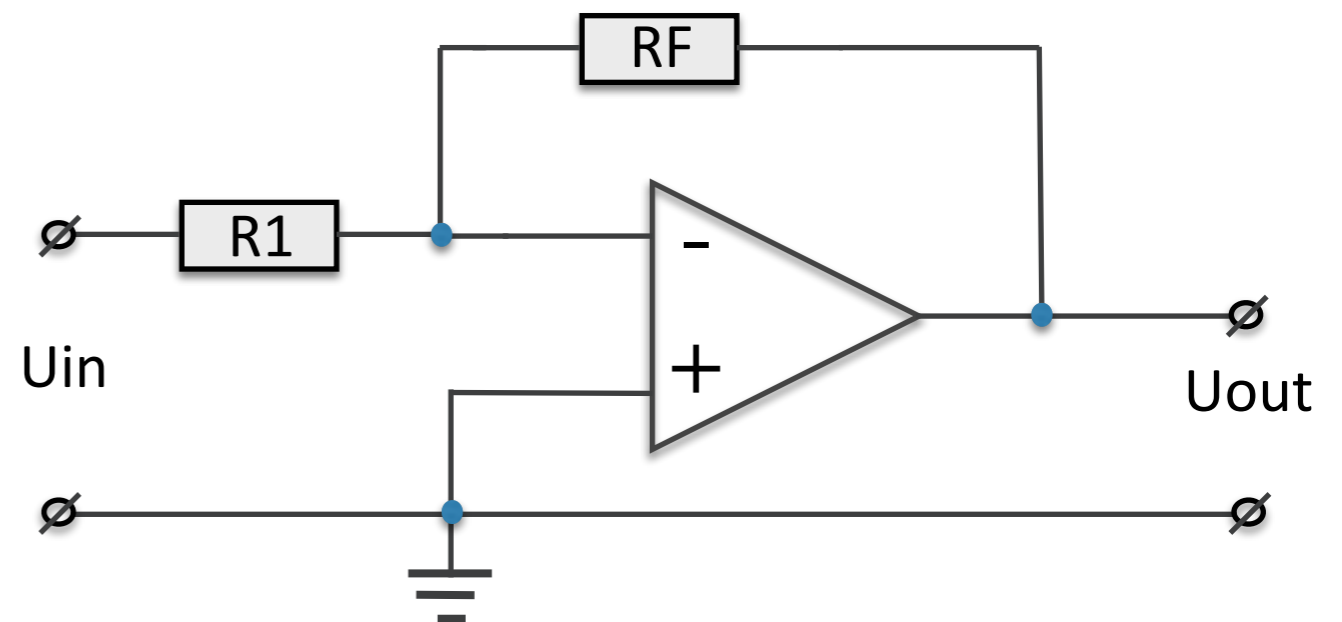
$$U_{in} = U_{out}$$



Some practical circuits, used in sensor world ...

Inverting Amplifier

Most common amplifier circuit. The combination (ratio) of R_f and R_1 , determine the amount of amplification. Because the signal is connected to the negative input, the **output values will be inverted!**



Some practical circuits, used in sensor world ...

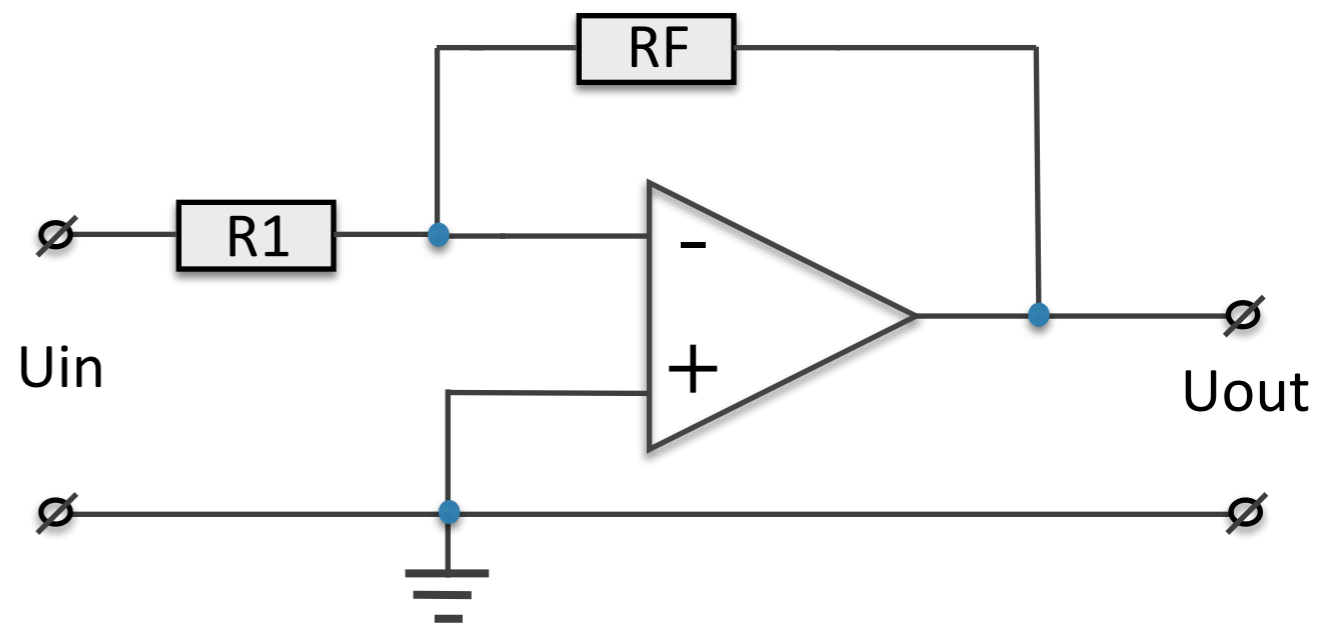
Inverting Amplifier

Most common amplifier circuit. The combination (ratio) of R_f and R_1 , determine the amount of amplification. Because the signal is connected to the negative input, the **output values will be inverted!**

$$A_u = \frac{U_{out}}{U_{in}} = - \frac{R_f}{R_1}$$

$$U_{out} = A_u * U_{in}$$

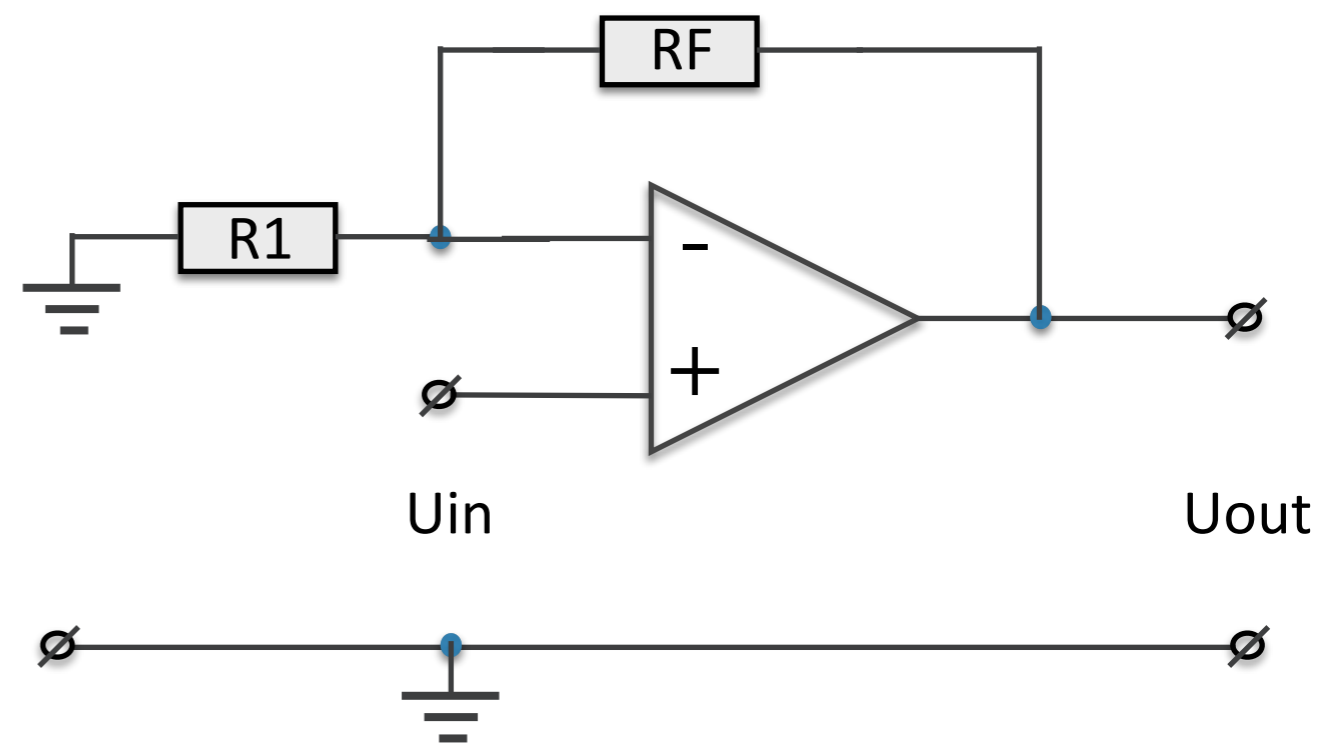
$$U_{out} = - \frac{R_f}{R_1} * U_{in}$$



Some practical circuits, used in sensor world ...

Non-inverting Amplifier

When the signal is connected to the positive input of the opamp, the amplified output is not inverted. The amplification of a non-inverting amplifier is always more than 1.



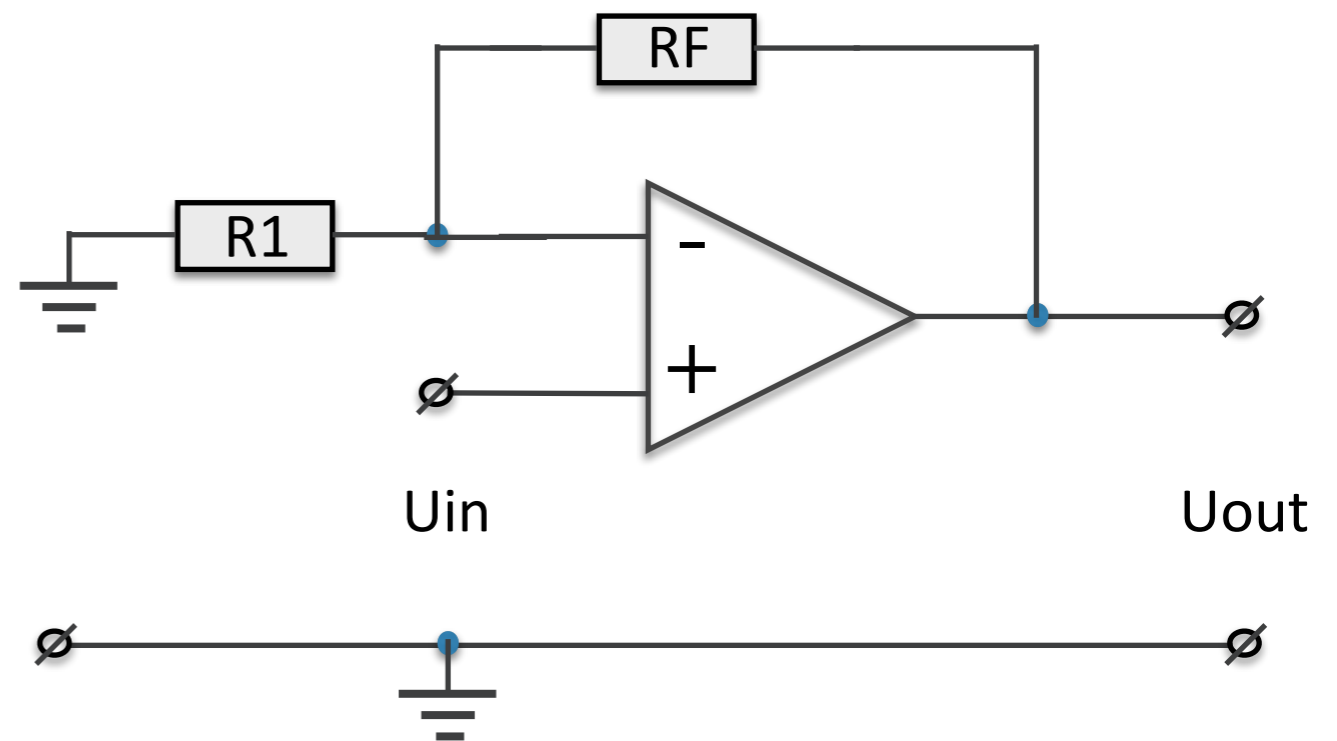
Some practical circuits, used in sensor world ...

Non-inverting Amplifier

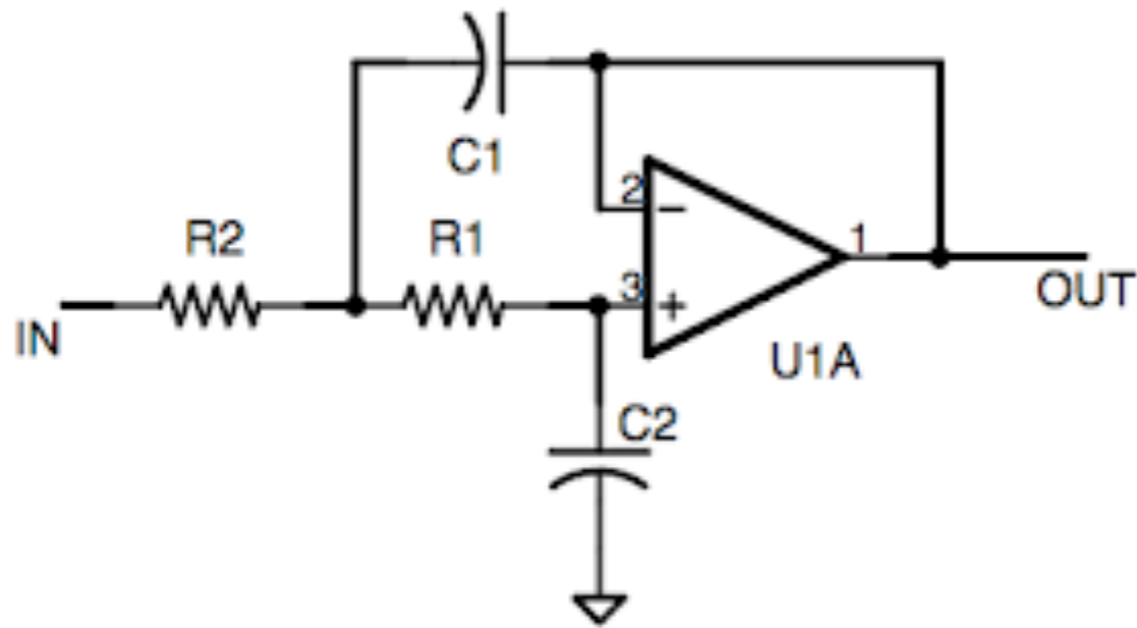
When the signal is connected to the positive input of the opamp, the amplified output is not inverted. The amplification of a non-inverting amplifier is always more than 1.

$$Au = \frac{U_{out}}{U_{in}}$$

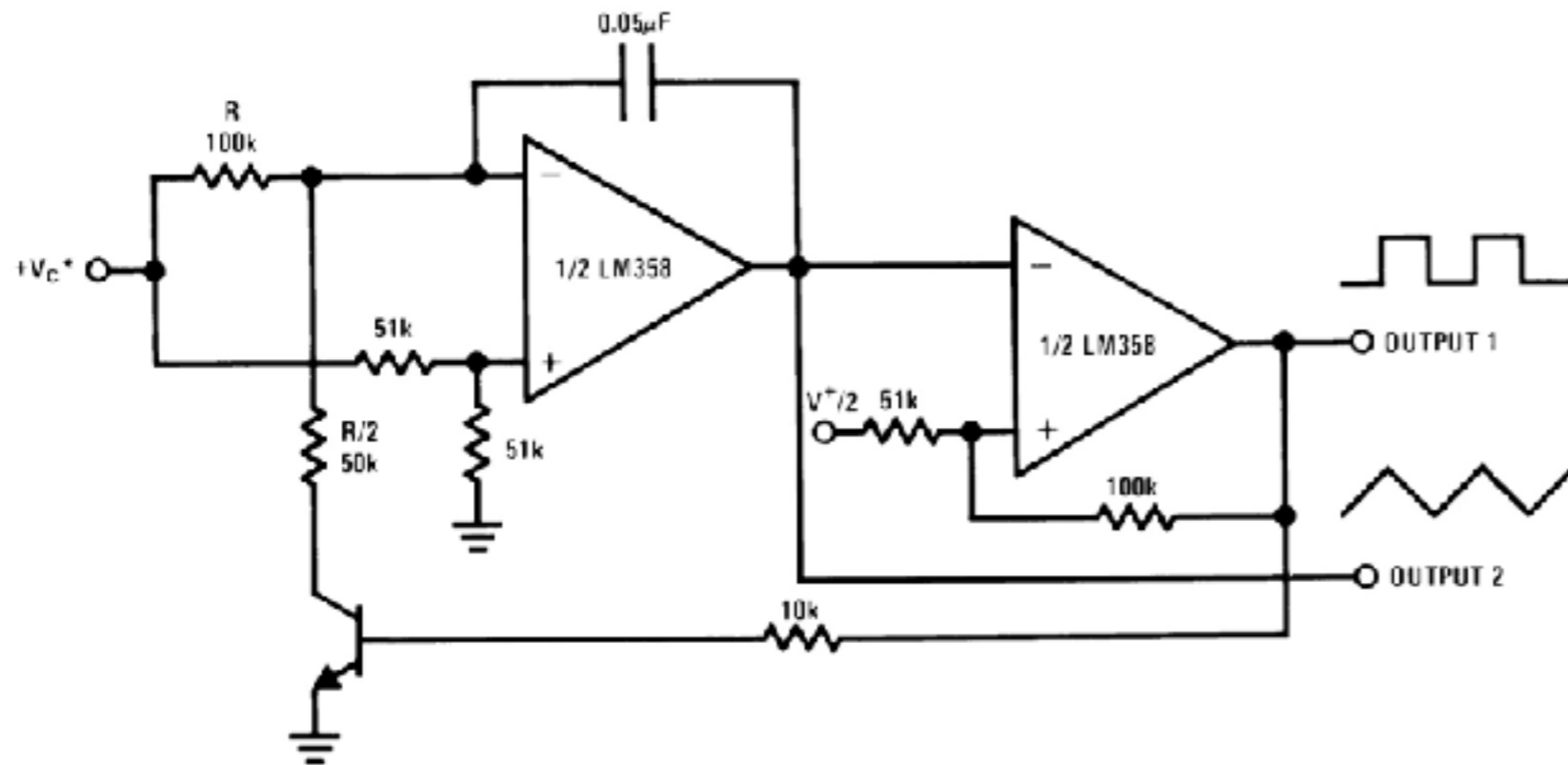
$$U_{out} = \left(1 + \frac{R_F}{R_1}\right) * U_{in}$$



Some random examples ...

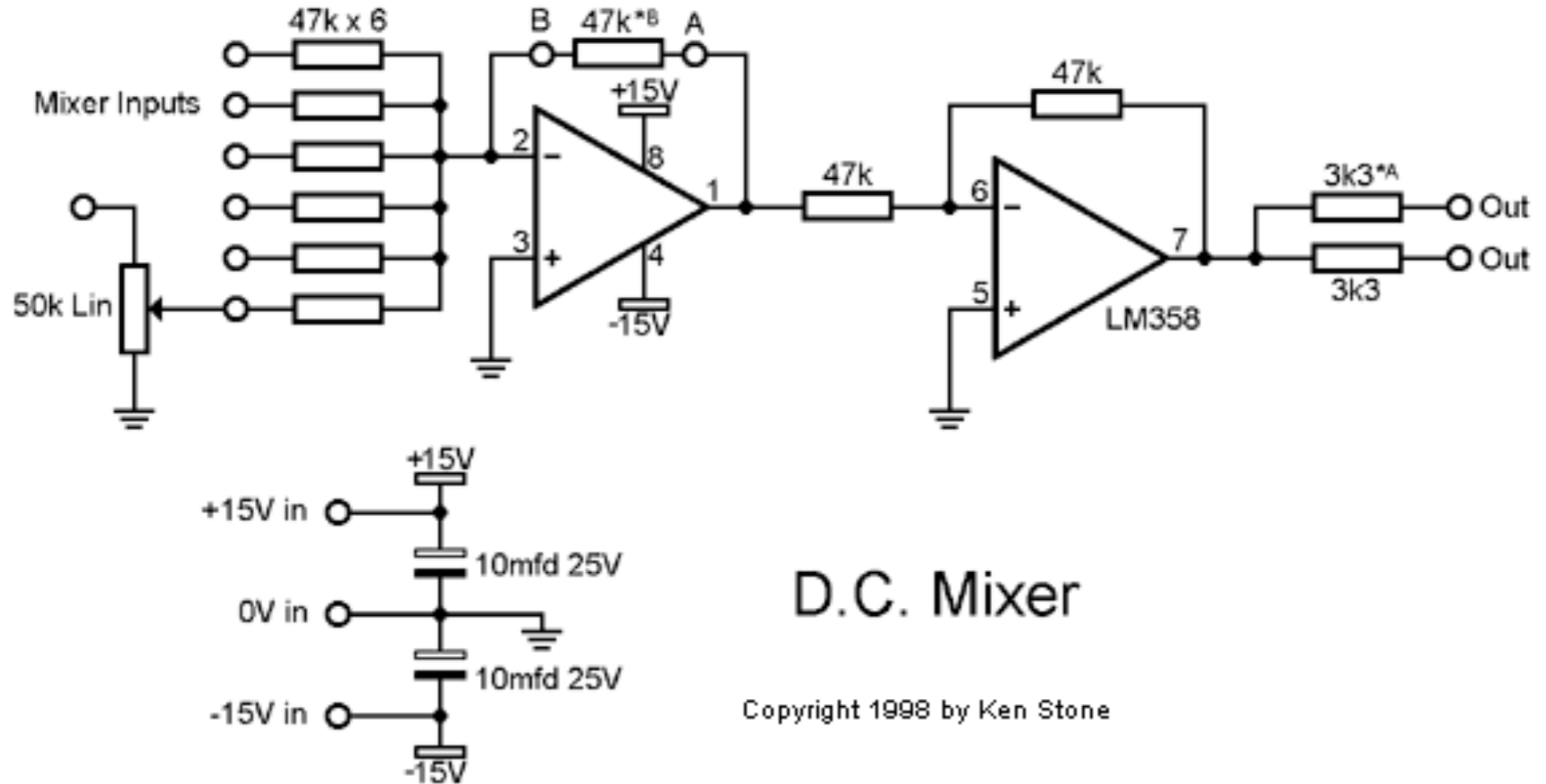


Active filter (LPF)



Voltage Controlled Oscillator

Some random examples ...



D.C. Mixer

Copyright 1998 by Ken Stone

Some random examples ...

LT1112 Power Connections

Pin 4 = -12V

Pin 8 = +12V

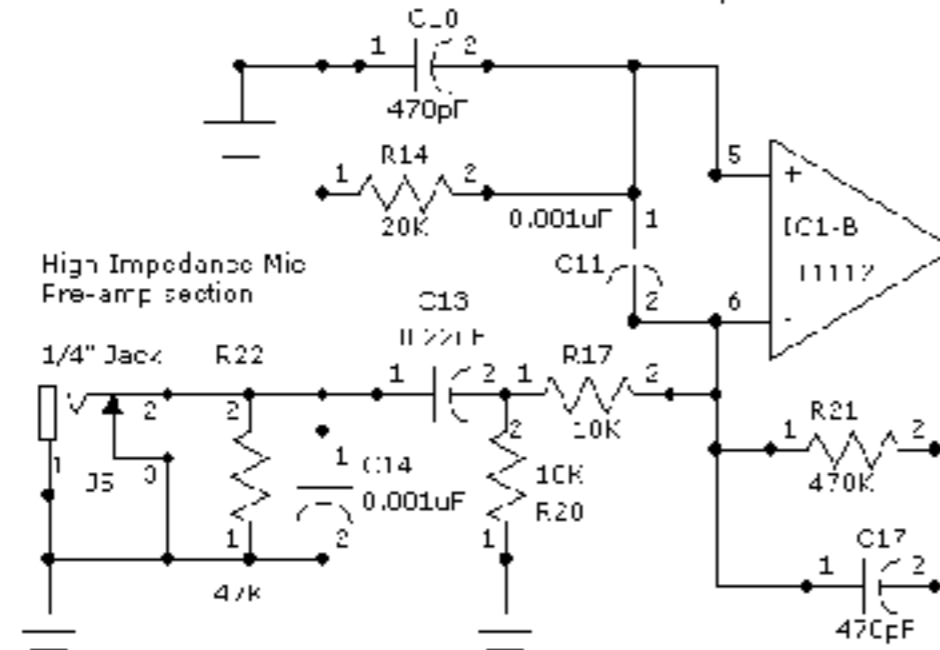
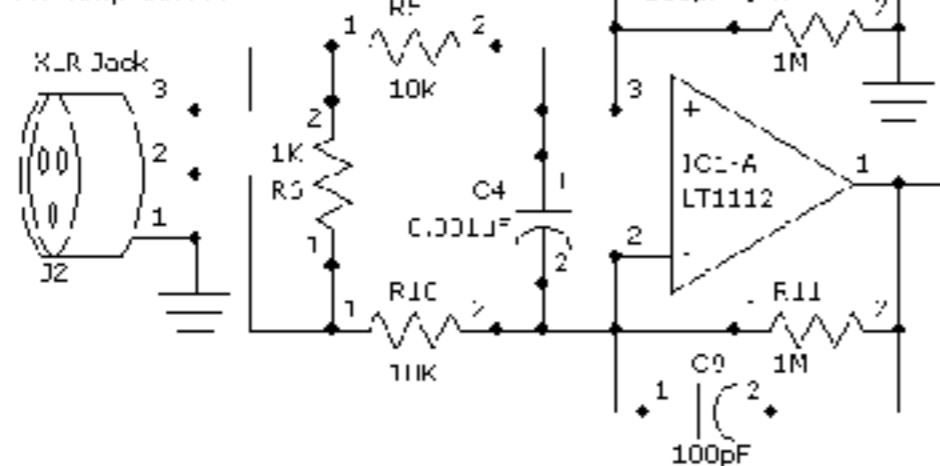
TL084 Power Connections

Pin 4 = +12V

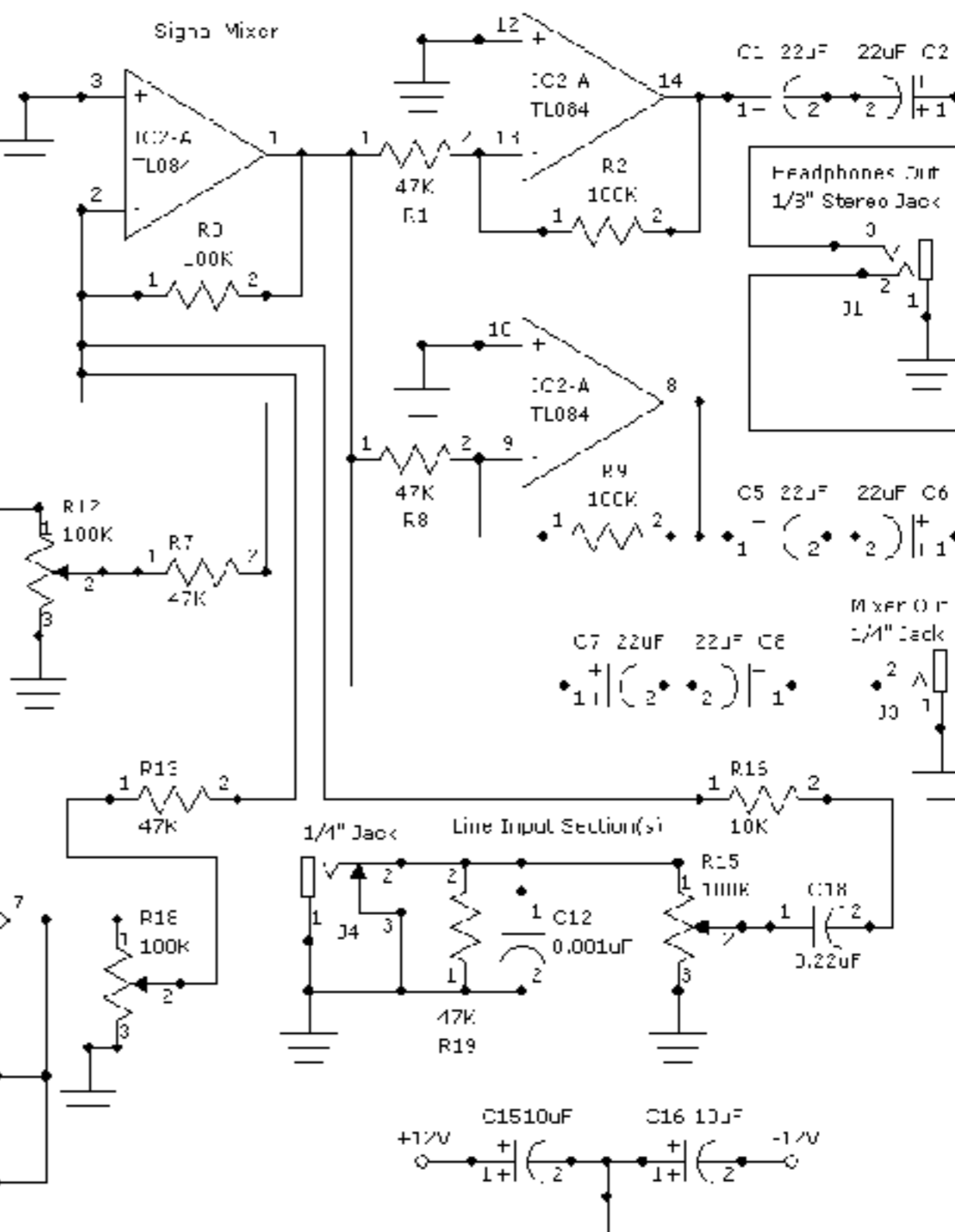
Pin 11 = -12V

Add as many sections of each type of input as you want. Each section is comprised of all components up to and including the mixing resistor connected to pin 2 of IC2-A

Low Impedance Mic Pre-amp section

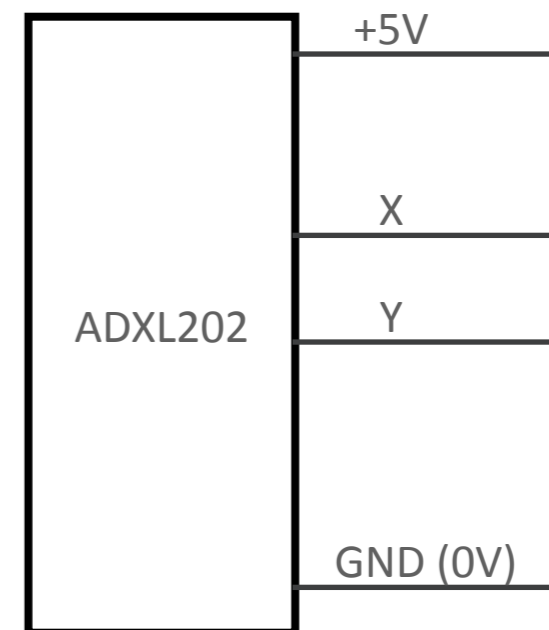
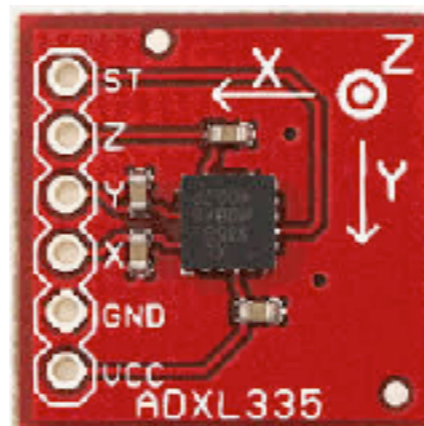


Signal Mixer

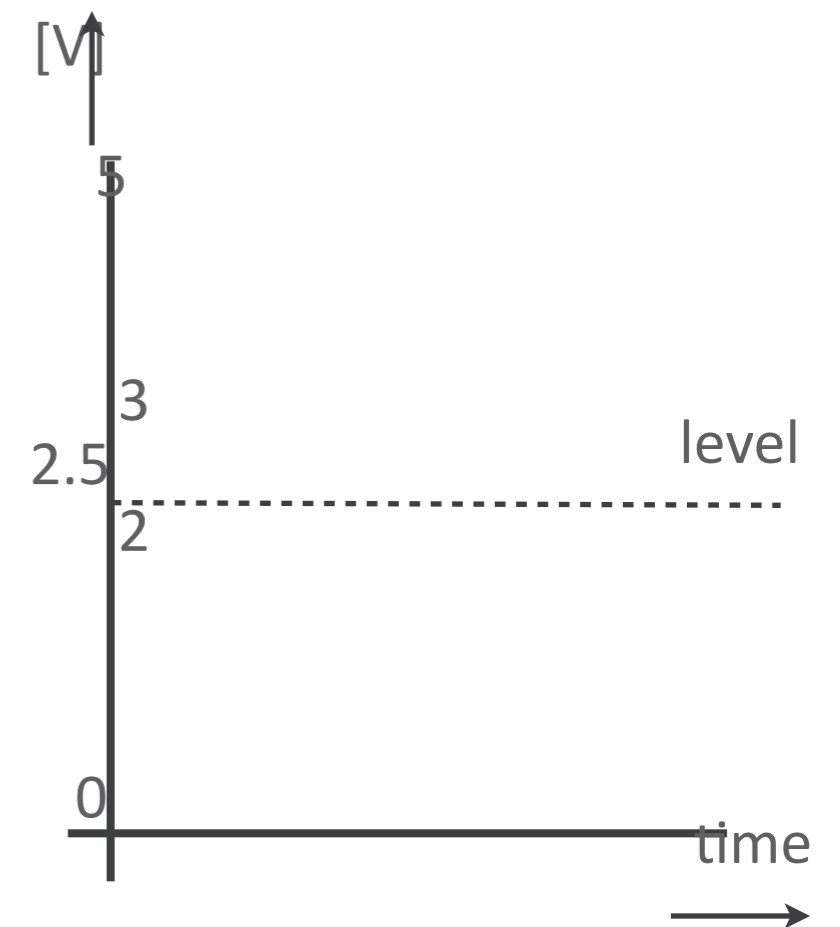
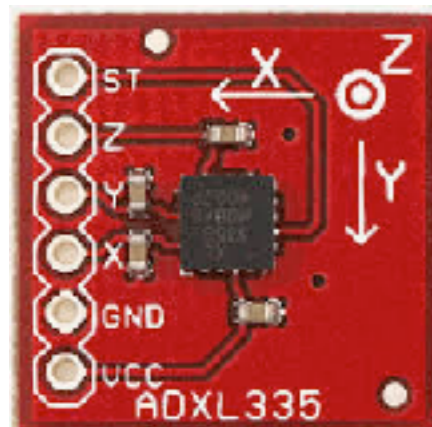


Amplify (condition) the output of an accelerometer

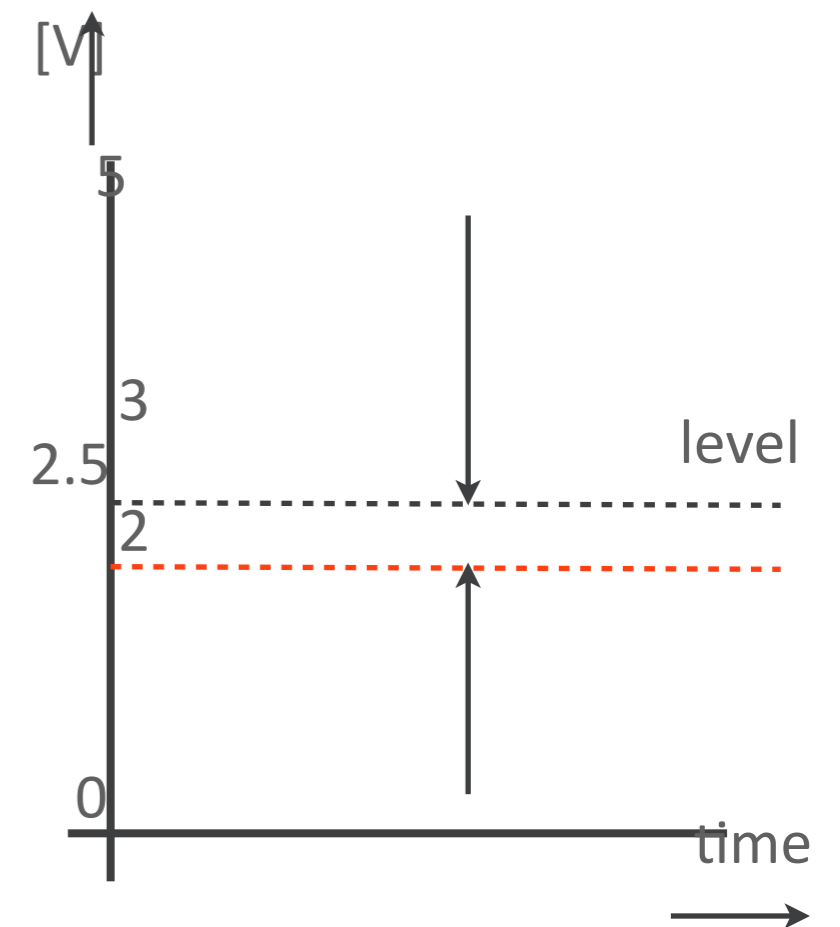
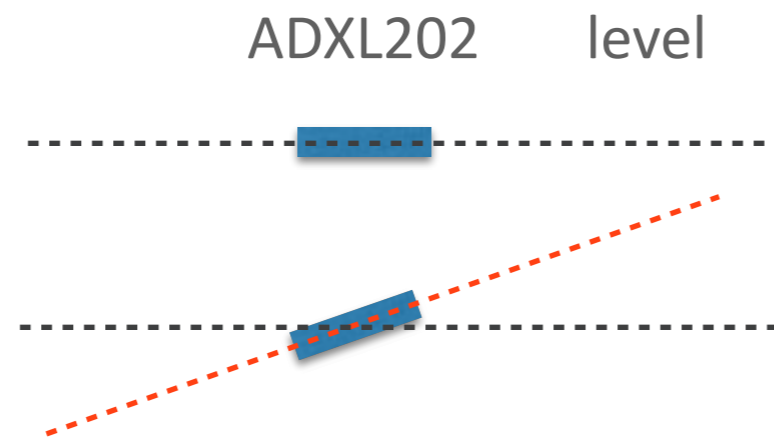
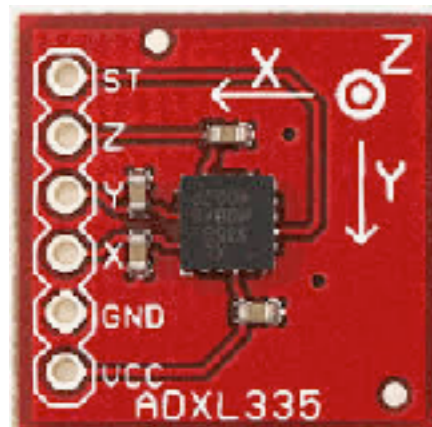
Let's try to connect a accelerometer; an ADXL202. What is an accelerometer? An **accelerometer** measures the proper acceleration it experiences relative to freefall. Single- and multi-axis models are available and can a.o. be used to sense orientation, vibration and shock. The ADXL202 is a dual axis model with two outputs, X and Y.



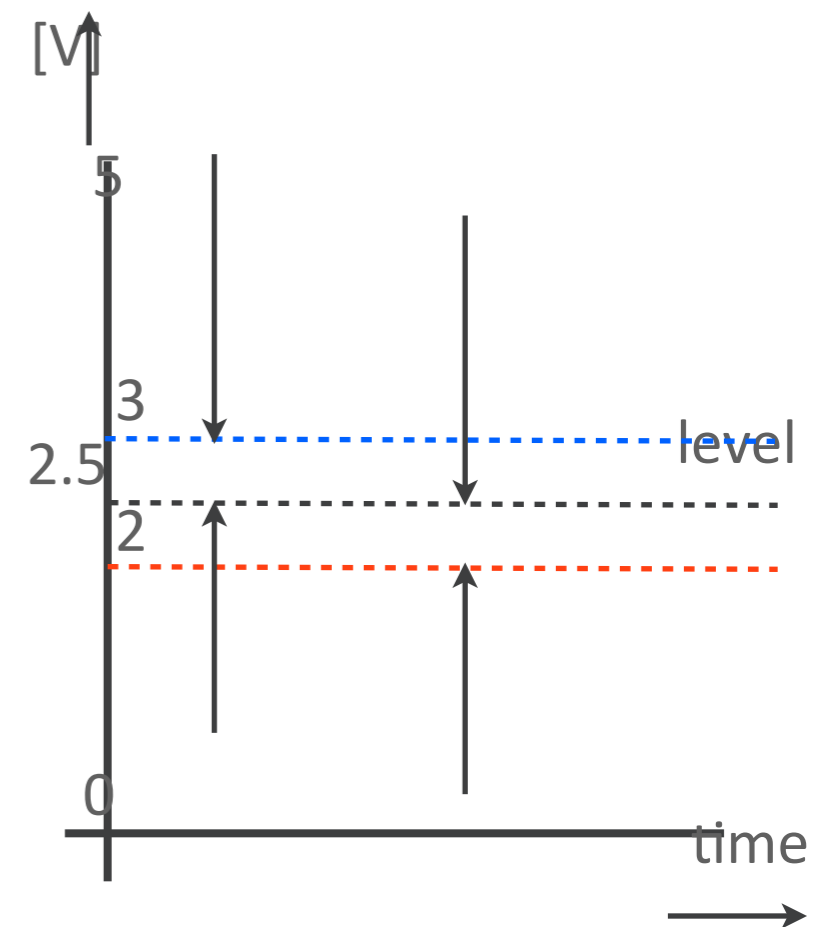
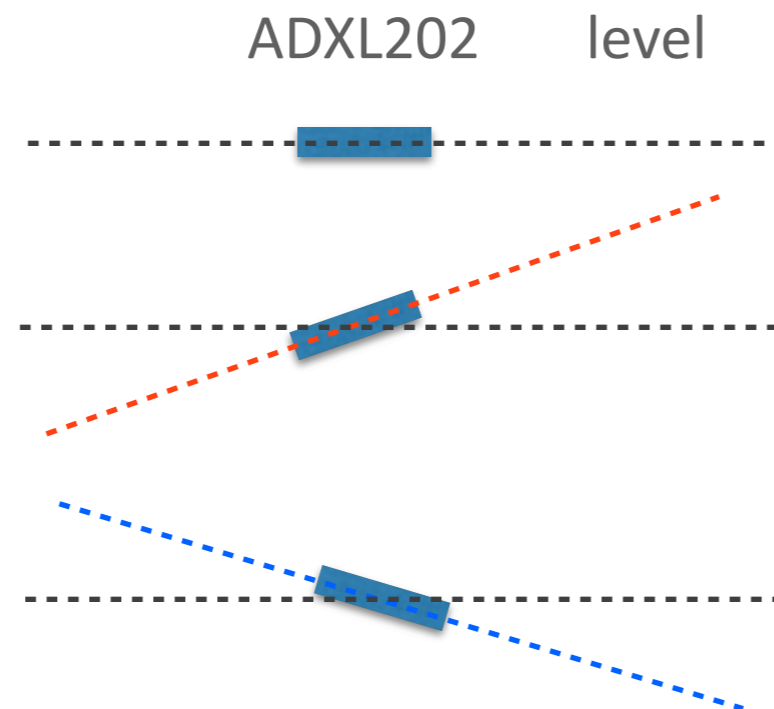
Amplify the output of an accelerometer



Amplify the output of an accelerometer

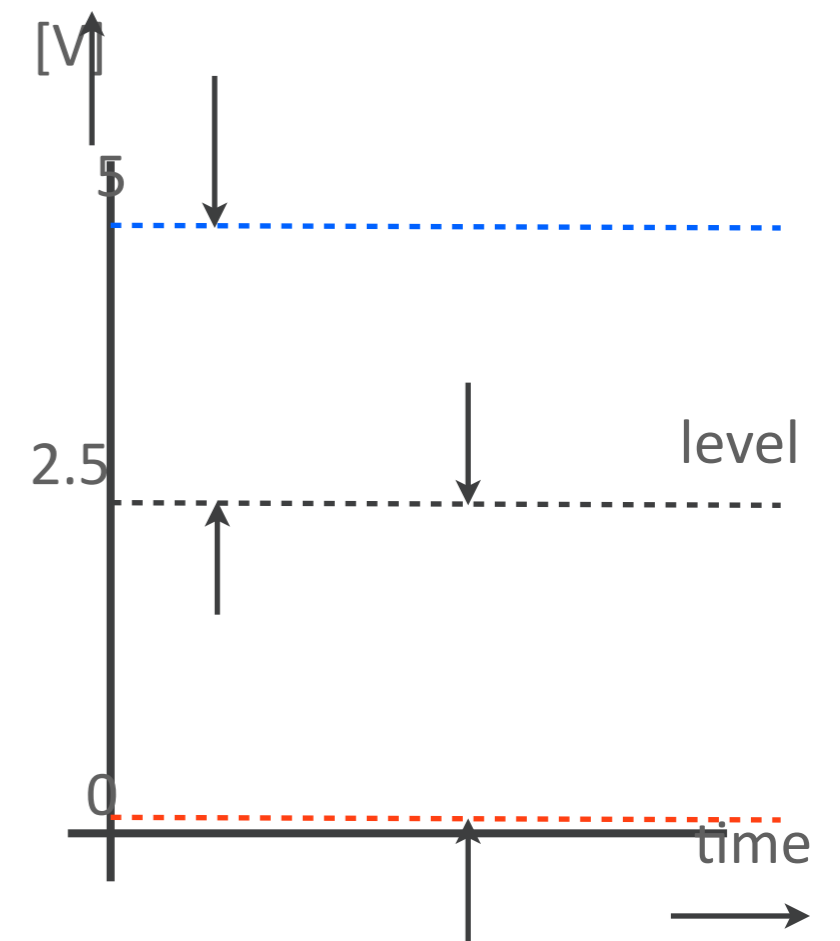
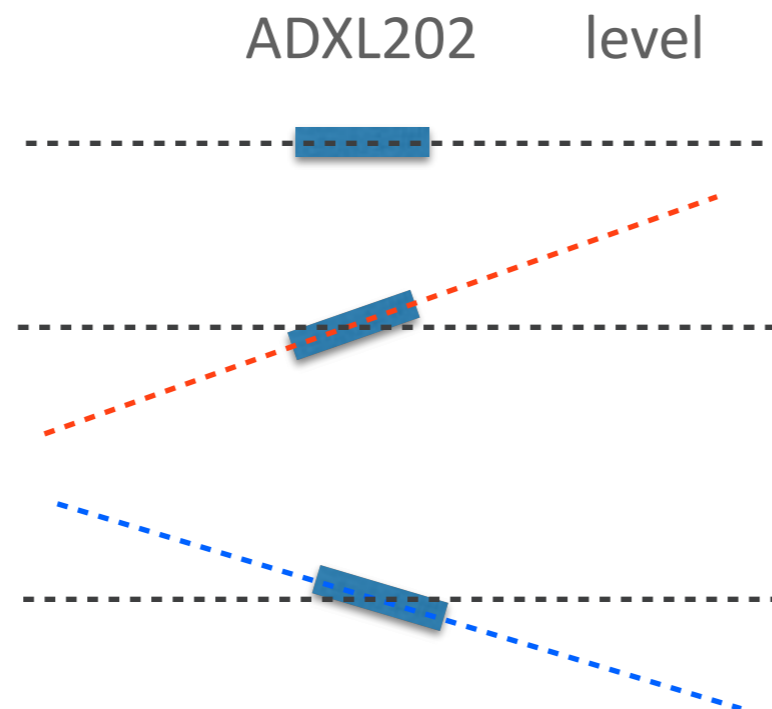
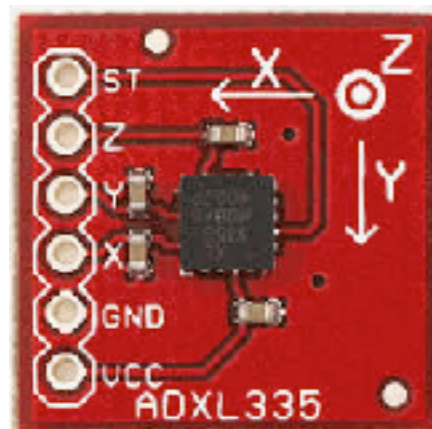


Amplify the output of an accelerometer

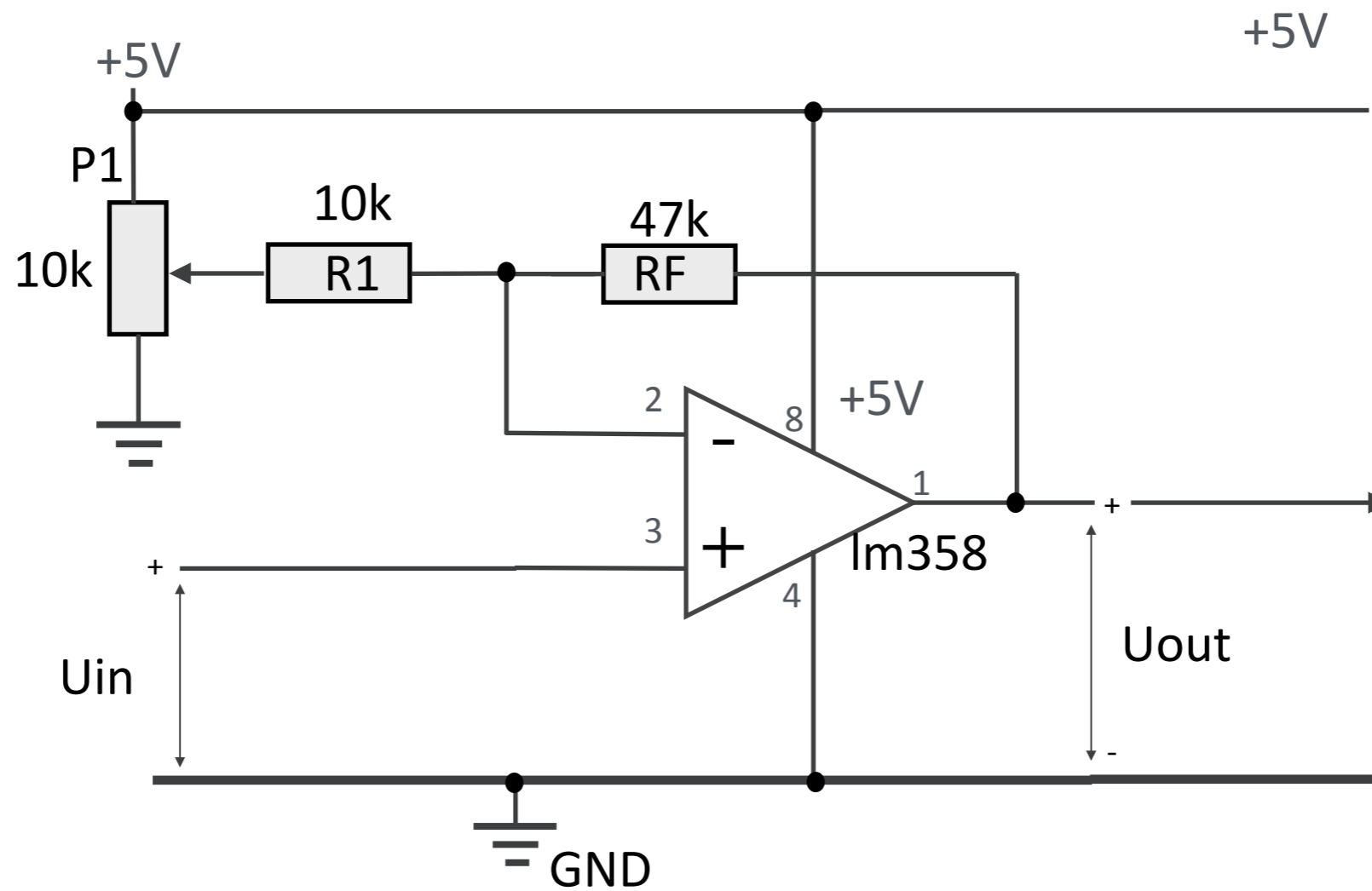


The voltage change (per rotation) is around 0,5V (500mV). This is enough to use the full scale (0-5V) of the Arduino. We have to amplify (condition) the signal.

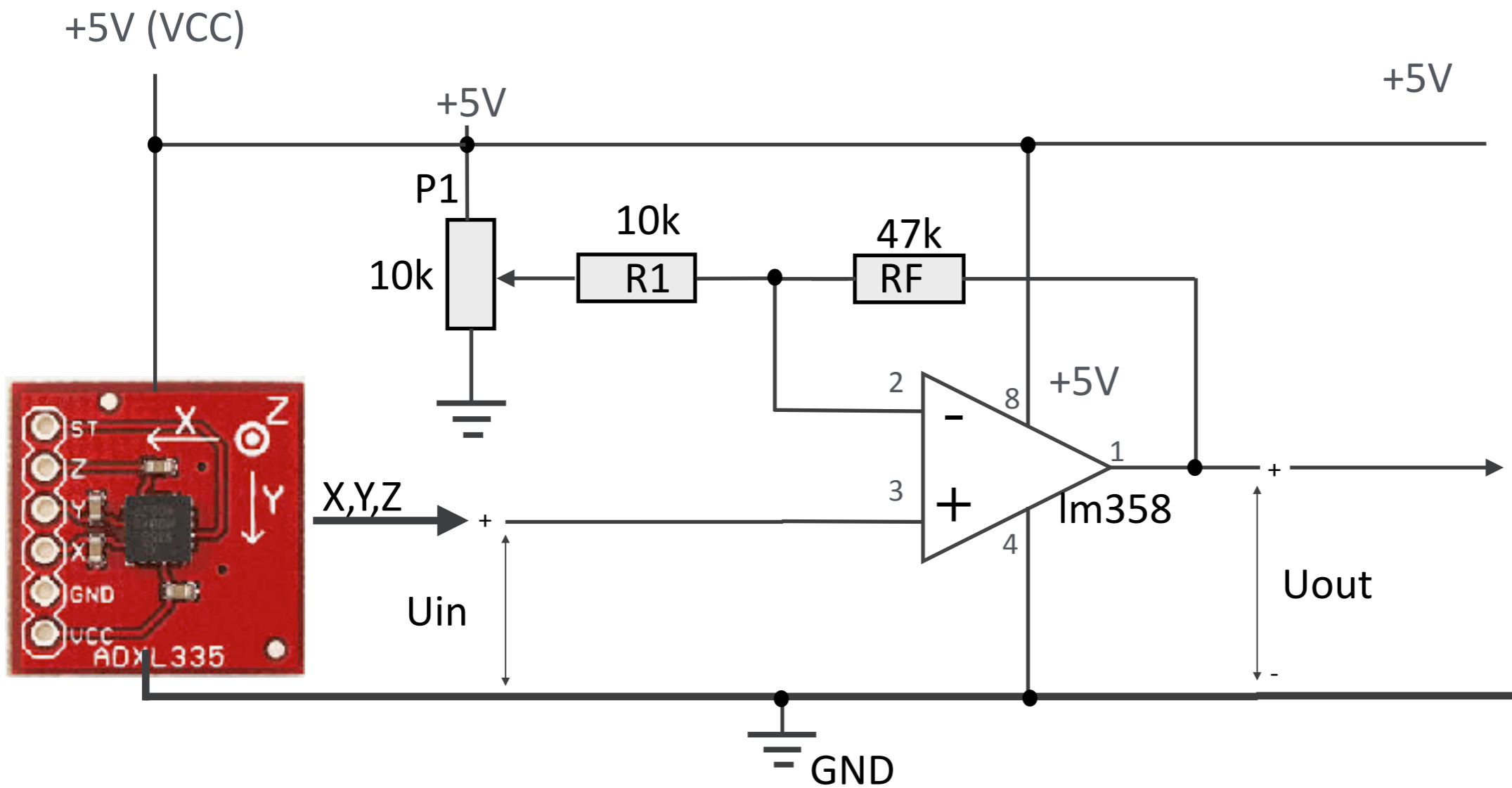
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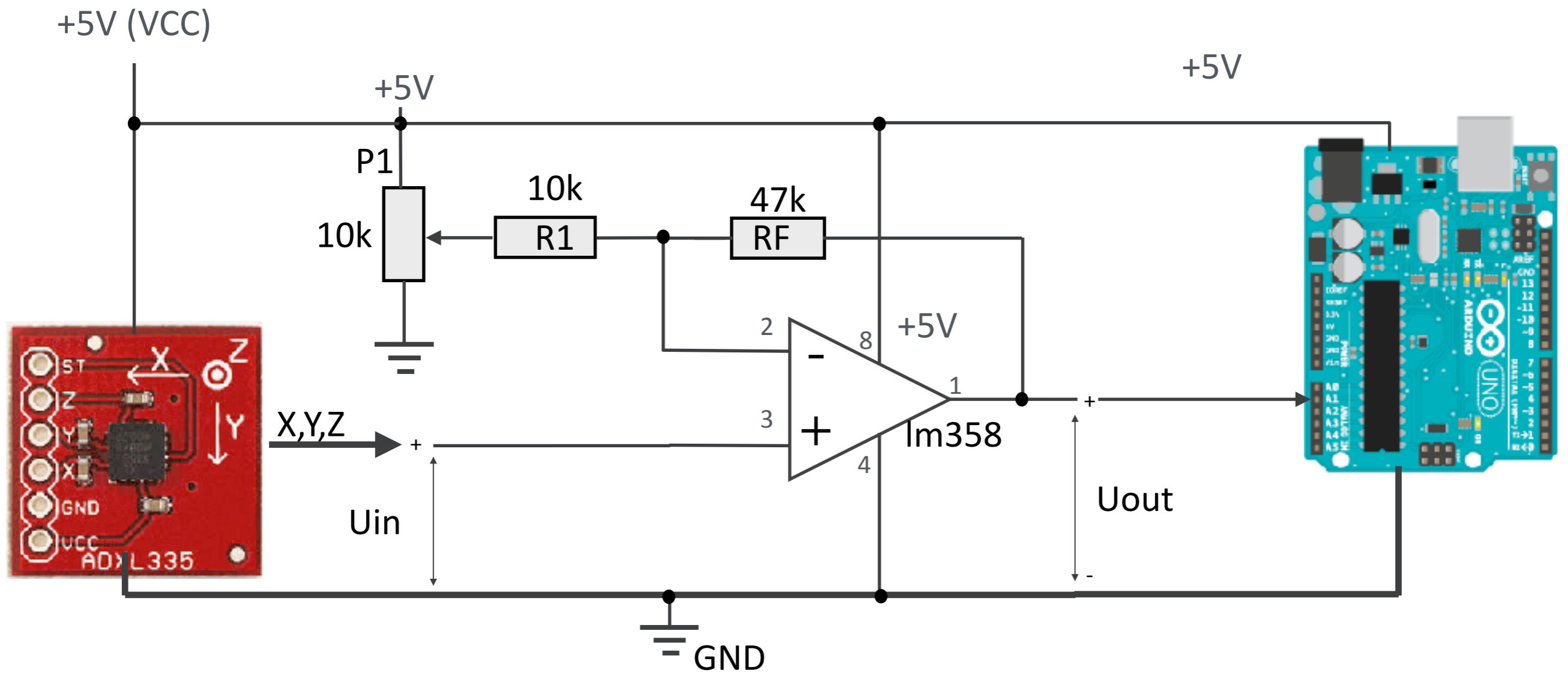
Non inverting amplifier (mono, so 1 signal only) with an offset trim (P1).



Non inverting amplifier (mono, so 1 signal only) with an offset trim (P1).



Non inverting amplifier (mono, so 1 signal only) with an offset trim (P1).



Sensors, Microcontrollers and Actuators

Opamps end.